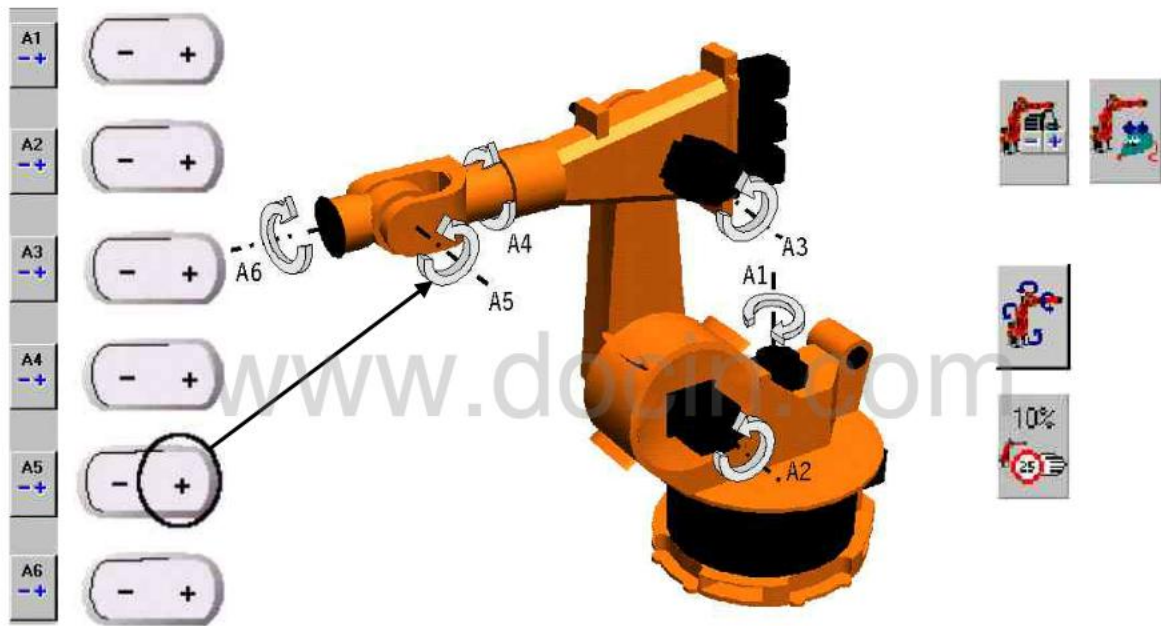
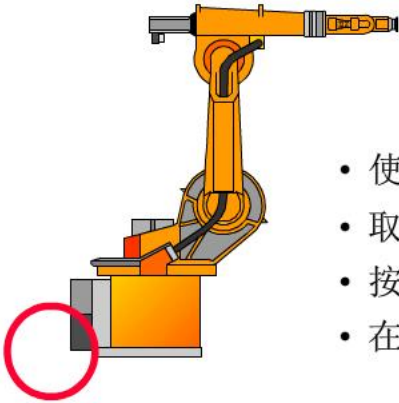


练习 1: 操作方式选择, 速度调整, 座标及机器人手动

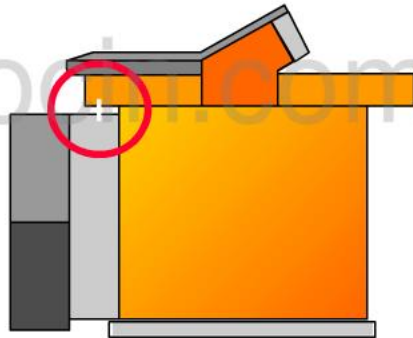


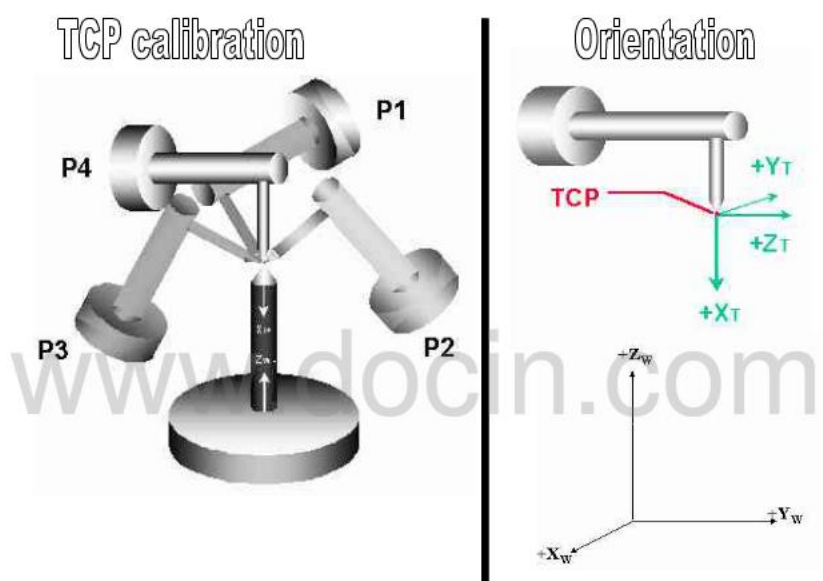
练习 2: 执行和停止程序

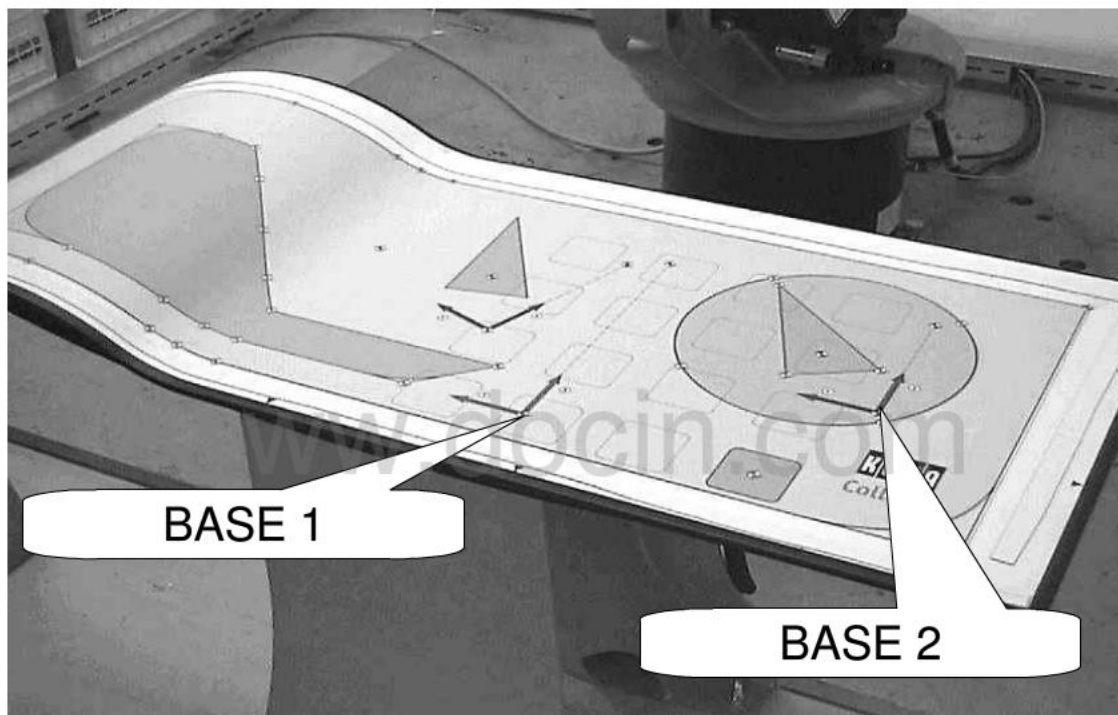


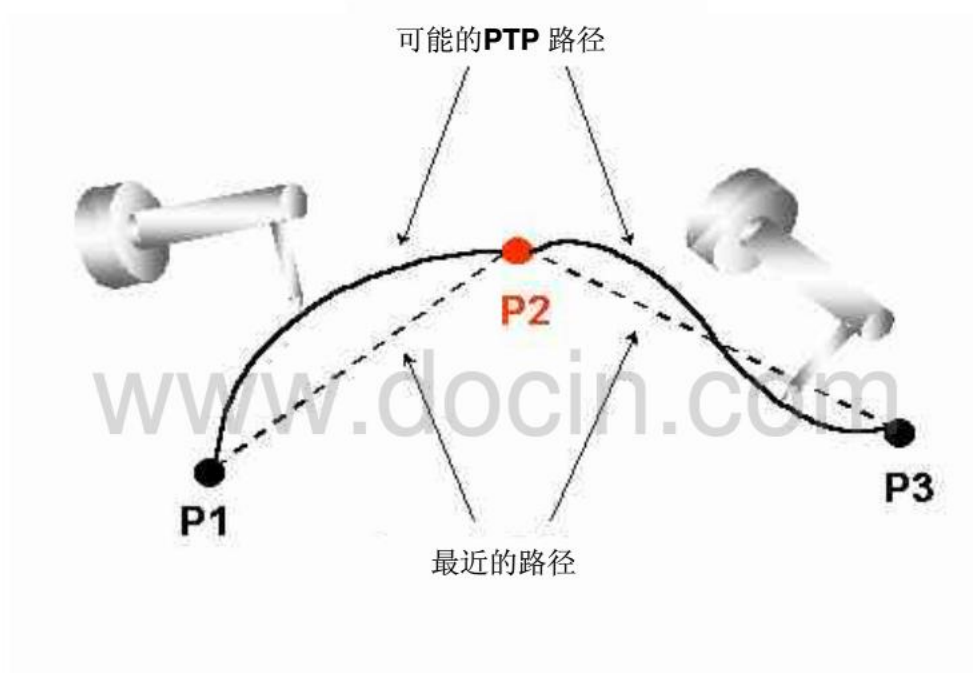


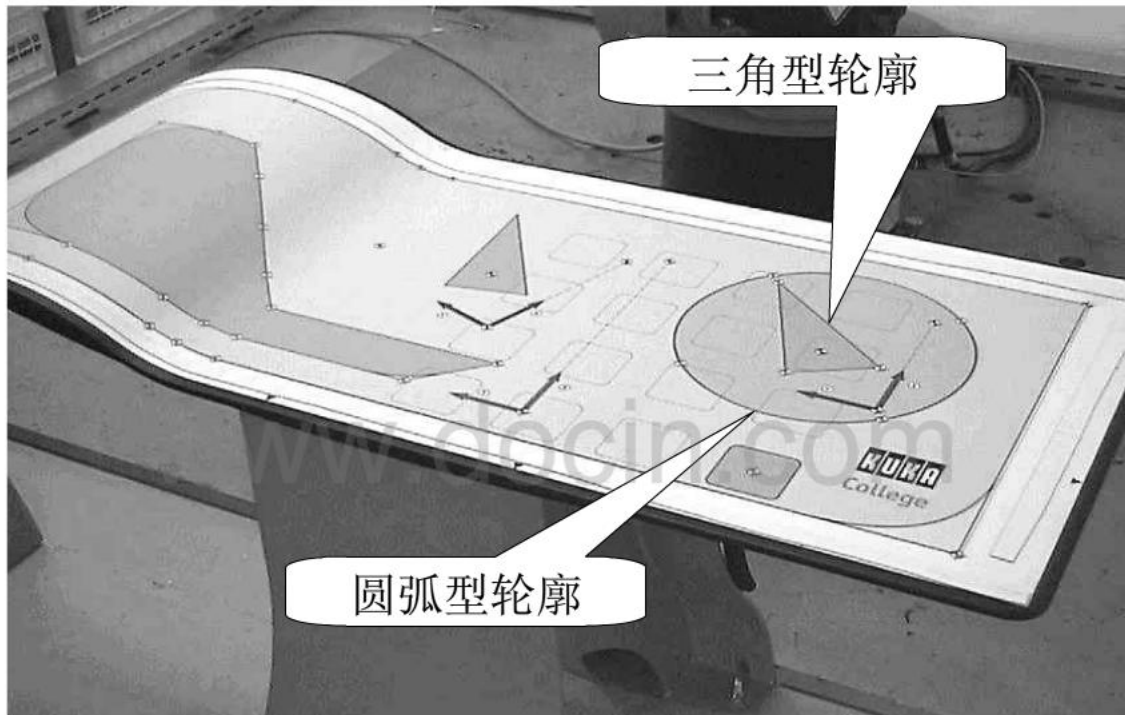
- 使用**EMT**
- 取消原有的零点，在各种坐标系下运行机器人
- 按要求设定机器人零点
- 在各种坐标系下手动运行机器人。与无零点时的运动进行比较

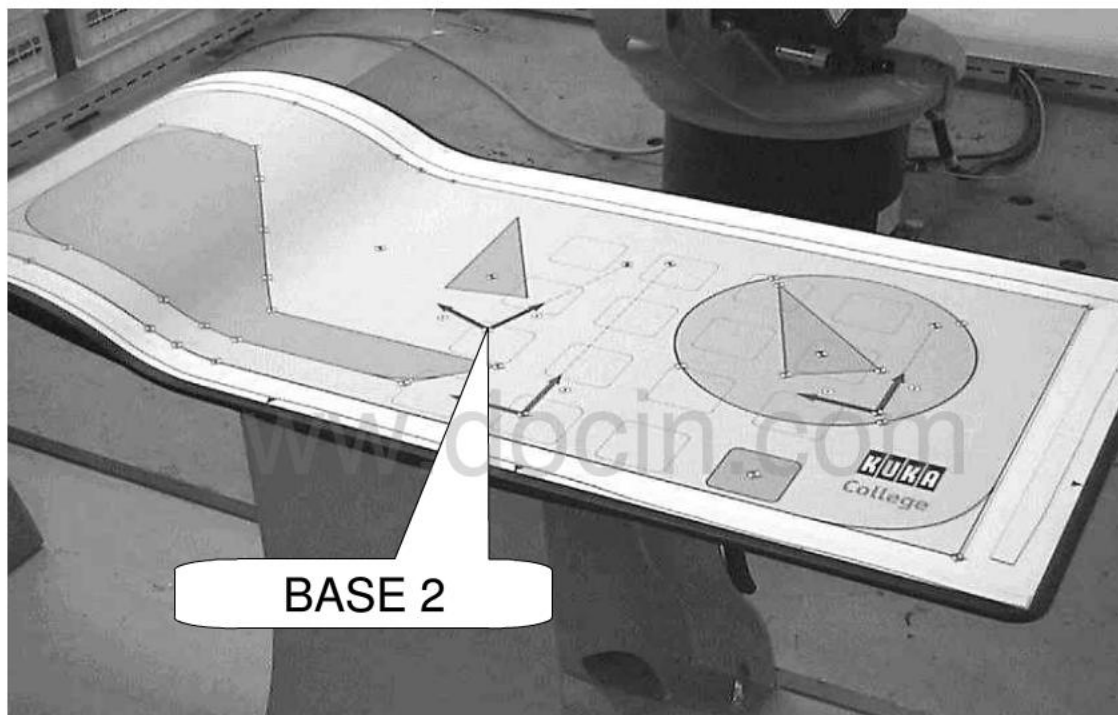


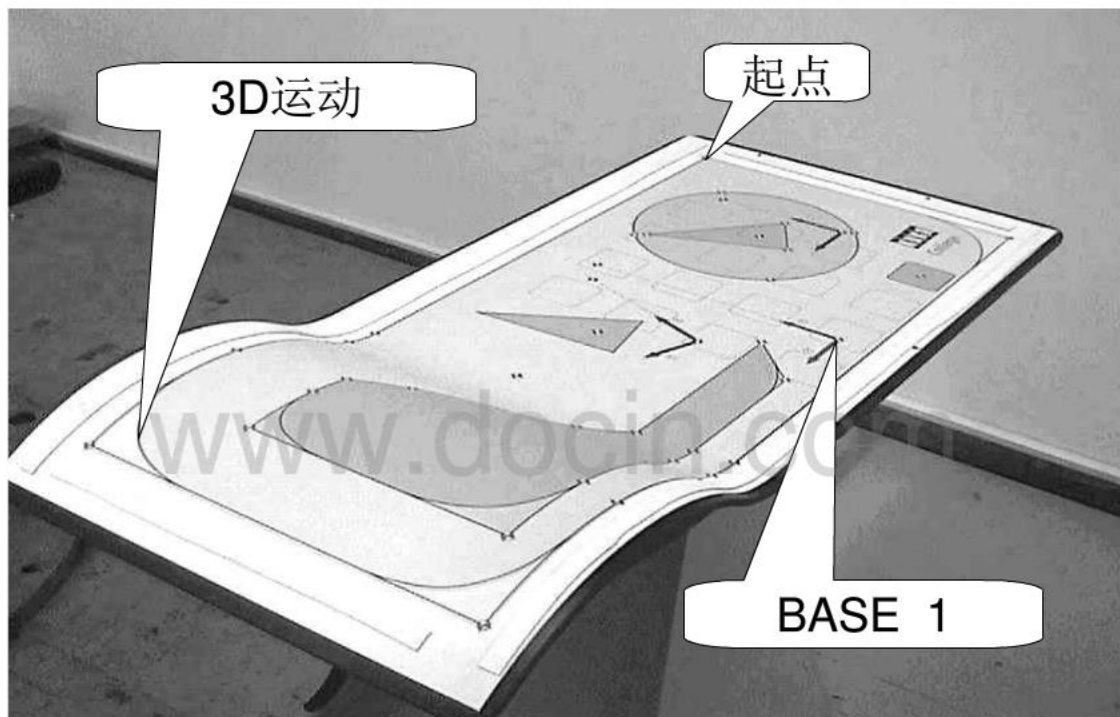




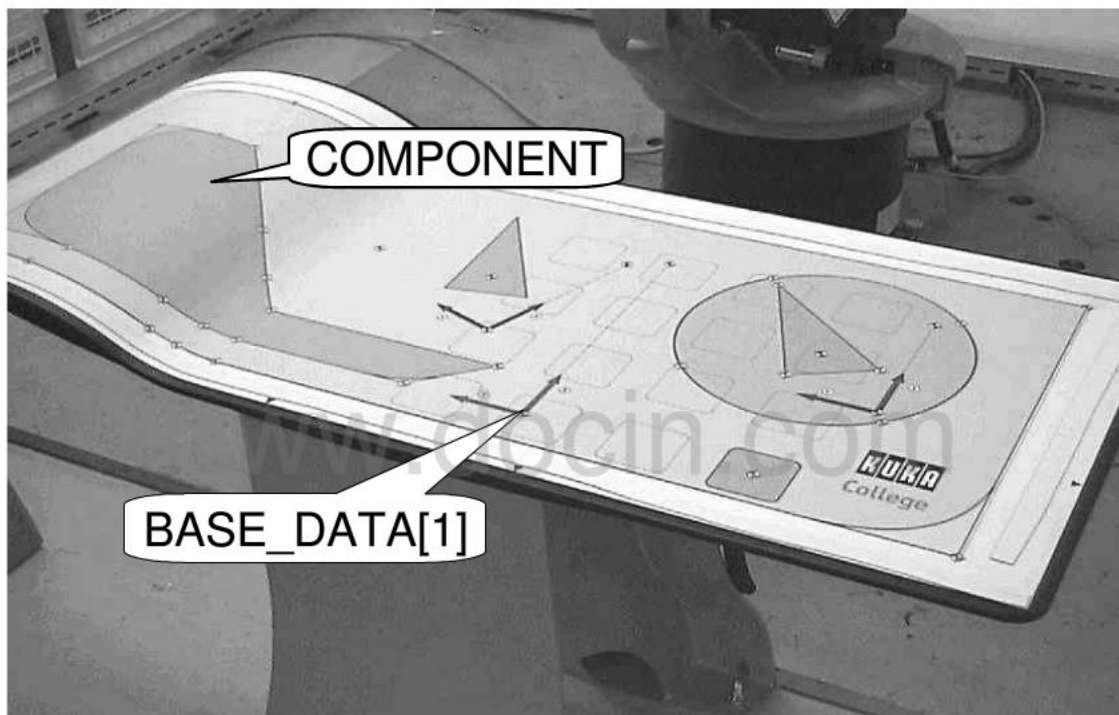






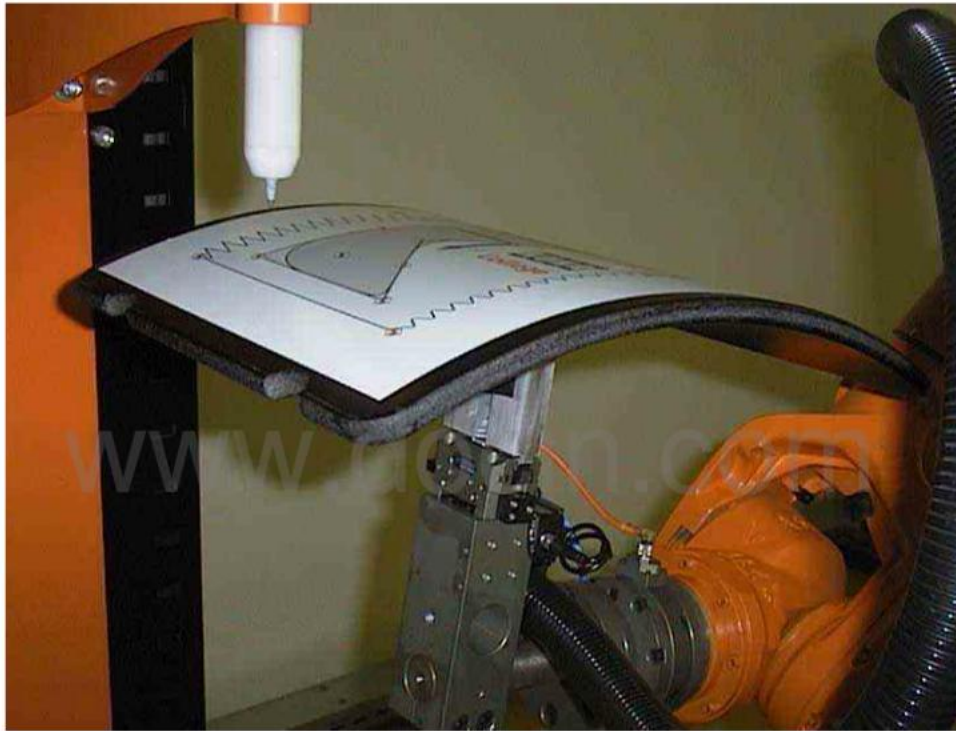


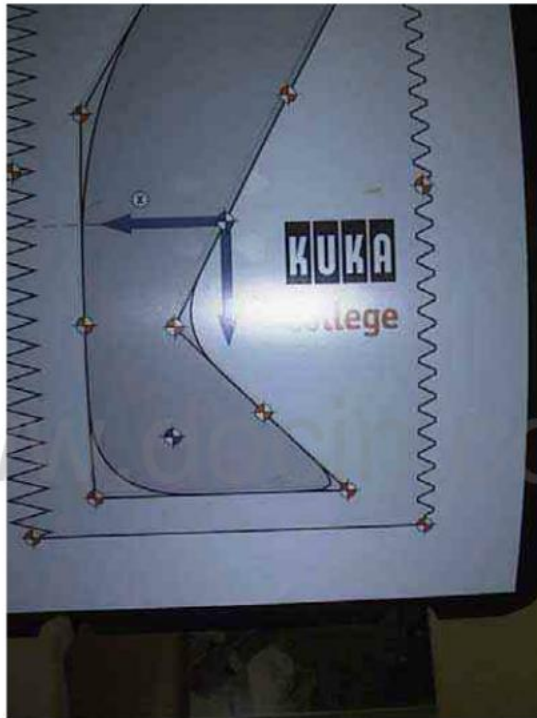


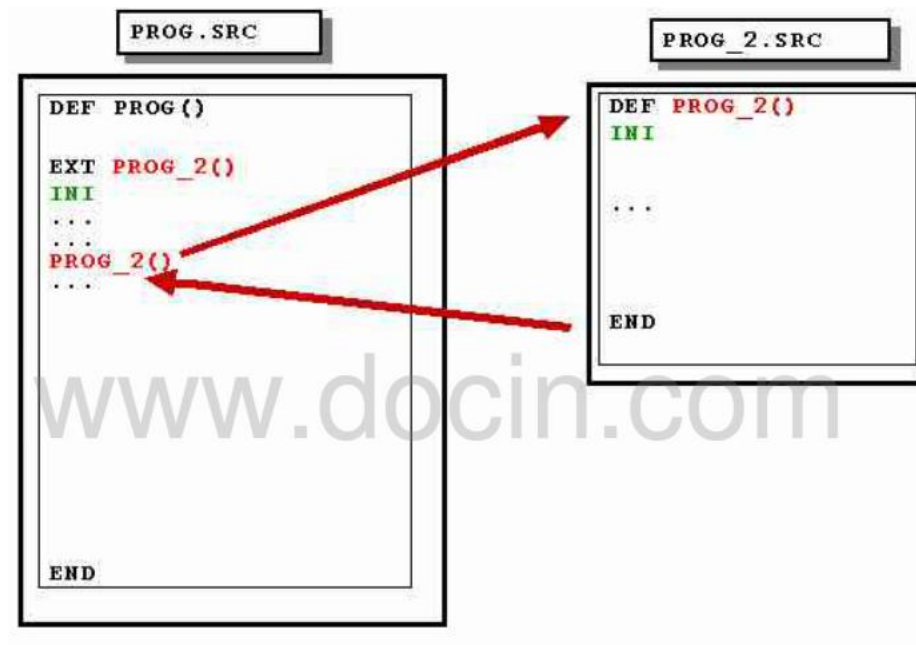


练习 12: 抛光 (塑料板)











Remove cube

Insert cube



练习 17: 子程序 (CP motion)

